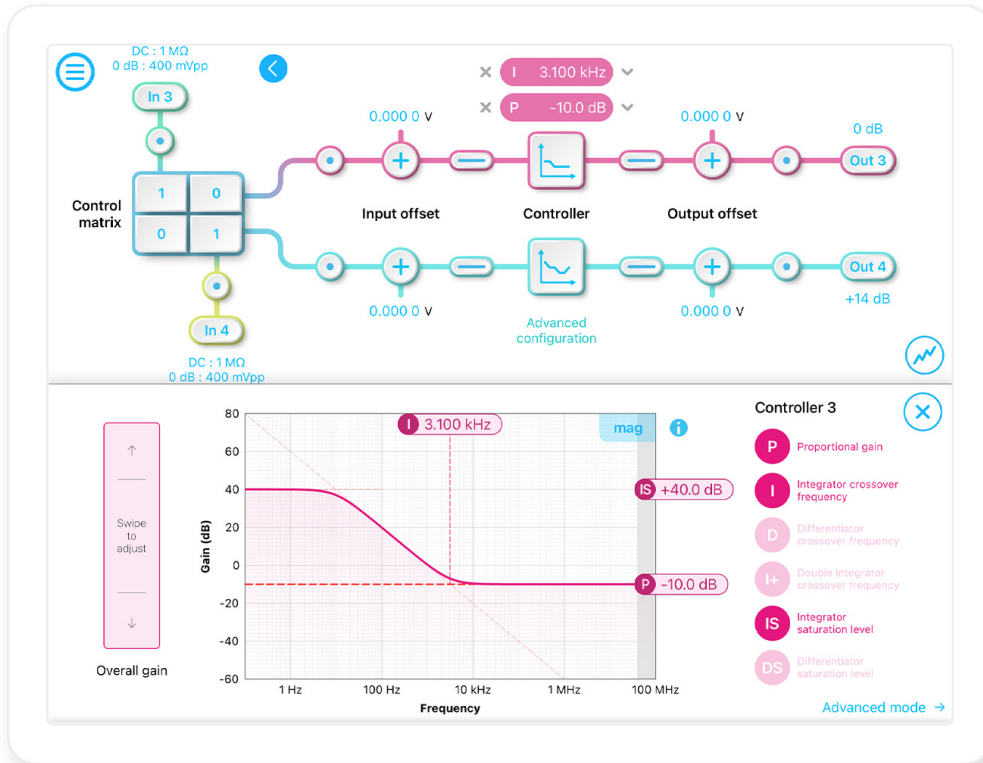




Moku:Pro's PID Controller features four fully configurable PID controllers with sub-microsecond latency. This enables them to be used in applications requiring both low and high feedback bandwidths such as laser temperature and current stabilization. The PID Controller can also be used as a lead-lag compensator by saturating the integral and differential controllers with independent gain settings.



Versatile input 4 inputs with MIMO	Proportional Gain - 60 dB to 60 dB	DAC resolution 16-bits	Input-output latency <1 $\mu$ s	Gain configuration Real-time	Advanced mode Multi-section builder
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## Features

- 4 input channels, 4 output channels, and 4 independent PID controllers with control matrix for MIMO
- Design your control system's frequency response using the interactive Bode plot in realtime
- Block diagram view of the digital signal processing with built-in probe points in signal processing chain
- Advanced multi-section PID builder with single or double integrators and differentiators with low- and high-frequency gain saturation
- Intergrated probe points for signal monitoring

## Specifications

- Control matrix linear gain:  $\pm 0.1$  to  $\pm 20$
- Input offset range:  $\pm 1$  V
- Output offset range:  $\pm 5$  V
- Offset precision: 100  $\mu$ V
- Gain profiles: Proportional (P), integral (I), differential (D), double-integral (+), integral saturation (IS), differential saturation (DS)
- Proportional gain: -60 dB to 60 dB
- Integrator crossover frequency: 3.125 Hz to 312.5 kHz
- Differentiator crossover frequency: 31.25 Hz to 31.25 MHz

## Applications

- Feedback and control systems design
- Laser frequency stabilization
- Temperature regulation
- Scan heads/sample stage positioning
- Pressure, force, flow rate, and other controls